

Faculty of Electrical Engineering, Mathematics and Computer Science
Applied Finite Elements, Mastermath
EXAM MAY 28, 2018: 13:30 – 16:30 O’Clock @ Minnaert Building,
Room MIN 0.11, Leuvenlaan 4, Utrecht University

1 We consider the following boundary value problem for $u = u(x, y)$ to be determined in $\Omega \subset \mathbb{R}^2$ (bounded by $\partial\Omega$) :

$$\begin{cases} \nabla \cdot [\mathbf{v}(x, y)u - D(x, y)\nabla u] = f(x, y), & \text{in } \Omega, \\ \mathbf{v}(x, y) \cdot \mathbf{n}u - D(x, y)\frac{\partial u}{\partial n} = g(x, y), & \text{on } \partial\Omega, \end{cases} \quad (1)$$

Here $\mathbf{v}(x, y)$, $f(x, y)$, $g(x, y)$ are given functions and $D = D(x, y) > 0$ in Ω .

- a Derive the compatibility condition for f and g . (1 pt)
- b Derive the weak formulation in which the order of spatial derivatives is minimized.
Hint: Keep the terms between the brackets as one expression. (2 pt)
- c Derive the Galerkin Equations to the weak form in part b. (1 pt)
- d We use linear triangular elements to solve the problem. All answers may be expressed in terms of the coefficients in the equations and in the coefficients in $\phi_i = \alpha_i + \beta_i x + \gamma_i y$ as well as in $|\Delta|$ being twice the area of element e .

- i Demonstrate the following formula for Newton-Cotes’ approximation for numerical integration:

$$\int_e h(x, y) d\Omega = \frac{|\Delta_e|}{6} \sum_{p \in \{1, 2, 3\}} h(x_p, y_p), \text{ for triangle } e \text{ with vertices } (x_p, y_p).$$

- Compute the element matrix and element vector for an internal triangle. (3 pt)

- ii Compute the element matrix and element vector for a boundary element. *Hint:* Use Newton–Cotes integration. (1 pt)

2 We consider bi-linear quadrilateral elements to solve a finite-element problem. In the element we define bi-linear basis functions $\phi_i(\mathbf{x})$ corresponding to the 4 vertices, with coordinates \mathbf{x}_p , $p \in \{1, 2, 3, 4\}$, which are used to approximate the solution. The basis-functions are defined through $\phi_i(\mathbf{x}_j) = \delta_{ij}$.

- a Explain why we cannot use the form $\phi_i(x, y) = a_i + b_i x + c_i y + d_i xy$ (*Hint:* one may consider the case $\mathbf{x}_1 = (1, 0)$, $\mathbf{x}_2 = (0, 1)$, $\mathbf{x}_3 = (-1, 0)$ and $\mathbf{x}_4 = (0, -1)$). (2 pt)
- b We use an iso-parametric transformation, which is defined by

$$(T) : \mathbf{x}(s, t) = \mathbf{x}_1(1-s)(1-t) + \mathbf{x}_2 s(1-t) + \mathbf{x}_3 s t + \mathbf{x}_4(1-s)t, \text{ with } s, t \in [0, 1],$$

to map the quadrilateral onto a reference square.

- i Consider the reference element $\tilde{e} = (0, 1) \times (0, 1)$, show that the Newton–Cotes Rule applied to a unit square, \tilde{e} , is given by

$$\int_{\tilde{e}} g(s, t) d\Omega = \frac{1}{4} (g(0, 0) + g(1, 0) + g(1, 1) + g(0, 1)). \quad (2)$$

(2 pt)

- ii The transformation (T) can be rearranged into

$$\mathbf{x}(s, t) = \mathbf{x}_1 + (\mathbf{x}_2 - \mathbf{x}_1)s + (\mathbf{x}_4 - \mathbf{x}_1)t + (\mathbf{x}_1 - \mathbf{x}_2 + \mathbf{x}_3 - \mathbf{x}_4)st.$$

Compute the Jacobian matrix of the transformation, $\frac{\partial(x,y)}{\partial(s,t)}$ and show that the determinant of the Jacobian of the transformation is given by

$$\det\left(\frac{\partial(x,y)}{\partial(s,t)}\right) = (x_2 - x_1 + A_x t)(y_4 - y_1 + A_y s) - (y_2 - y_1 + A_y t)(x_4 - x_1 + A_x s),$$

with $A_x = x_1 - x_2 + x_3 - x_4$ and $A_y = y_1 - y_2 + y_3 - y_4$, and compute the determinant of the Jacobian on the four vertices that were given in assignment 1a. (2 pt)

- iii Compute the Jacobian matrix of the inverse transformation. Evaluate the inverse Jacobian matrix on the vertices \mathbf{x}_1 , \mathbf{x}_2 , \mathbf{x}_3 and \mathbf{x}_4 given in assignment 1a. (2 pt)
- c i Let ϕ_1 , ϕ_2 , ϕ_3 and ϕ_4 be the bilinear basis-functions over quadrilateral element e . Show that $\nabla\phi_i = \begin{pmatrix} \frac{\partial(s,t)}{\partial(x,y)} \end{pmatrix}^T \nabla_{st}\phi_i$, where $\nabla_{st}\phi_i$ is the gradient vector with partial derivatives of ϕ_i with respect to s and t . (1 pt)
- ii Use the Newton-Cotes Rule to compute $S_{11}^e = \int_e \|\nabla\phi_1\|^2 d\Omega$, where e is a quadrilateral with vertices \mathbf{x}_1 , \mathbf{x}_2 , \mathbf{x}_3 and \mathbf{x}_4 that were defined in assignment 1a. (2 pt)
- d What is the size of the element matrix for an internal quadrilateral element if a single partial differential equation is solved? Motivate the answer. (1 pt)

$$\text{Written Exam Grade} = \max\left(\frac{\text{Sum over all credits}}{2}, 1\right).$$