

T<sub>2</sub> 24-04-2013

**Question 1 (40 points)** A linear system  $Ax = b$  is solved, with  $A \in \mathbb{R}^{n \times n}$  and  $b \in \mathbb{R}^n$  given.

- (a) (10 p) Write down the right-preconditioned system  $\tilde{A}\tilde{x} = \tilde{b}$  for a preconditioner matrix  $M \in \mathbb{R}^{n \times n}$ —more precisely, specify  $\tilde{A}$ ,  $\tilde{x}$ ,  $\tilde{b}$  in terms of  $A$ ,  $x$ ,  $b$  and  $M$ .

$$Ax = b \rightarrow \underbrace{AM^{-1}}_{\tilde{A}} \underbrace{Mx}_{\tilde{x}} = \underbrace{b}_{\tilde{b}}$$

- (b) (15 p) Write down the (unpreconditioned) Richardson method for solving the right-preconditioned system given above. After that rewrite the Richardson method in terms of  $A$ ,  $x$ ,  $b$  and  $M$ .

$$\tilde{x}_{k+1} = \tilde{x}_k + \tilde{r}_k \quad \text{or} \quad \tilde{x}_{k+1} = \tilde{x}_k + \tilde{b} - \tilde{A}\tilde{x}_k$$

unprec. Richardson  $\nearrow$

$$\tilde{x}_{k+1} = \tilde{x}_k + \tilde{b} - \tilde{A}\tilde{x}_k$$

$$Mx_{k+1} = Mx_k + b - AM^{-1}Mx_k$$

$$Mx_{k+1} = Mx_k + b - Ax_k$$

$$x_{k+1} = x_k + \underbrace{M^{-1}(b - Ax_k)}_{r_k}$$

- (c) (15 p) For which choice of  $M$  will the Richardson iteration converge in the fastest possible way? Motivate your answer.

For  $M = A$  convergence in one iteration:  
given  $x_0$  and  $r_0 = b - Ax_0$

$$x_1 = x_0 + M^{-1}r_0 = x_0 + A^{-1}r_0 =$$

$$= x_0 + A^{-1}(b - Ax_0) = x_0 + A^{-1}b - x_0 = \underbrace{A^{-1}b}_{\text{exact solution}}$$

**Question 2 (30 points)** For a matrix  $A \in \mathbb{R}^{n \times n}$  it is known that all its Rayleigh quotients lie on the line  $2 + i\beta$  in the complex plane, with  $\beta \in \mathbb{R}$  and  $i^2 = -1$ . The line is thus parallel to the imaginary axis and crosses the real axis at point  $2 + i0 = 2$ . Is it true that the Ritz values of  $A$  will also lie on the line  $2 + i\beta$ ? Why or why not?

Ritz values of  $A$  are the eigenvalues of  $H_m = V_m^* A V_m$

$$\begin{aligned} \text{Rayleigh quot.} &= \left\{ \frac{(Ax, x)}{(x, x)} \mid x \neq 0 \right\} \supset \left\{ \frac{(Ax, x)}{(x, x)} \mid x = V_m y, y \in \mathbb{C}^m, y \neq 0 \right\} = \\ &= \left\{ \frac{(AV_m y, V_m y)}{(V_m y, V_m y)} \mid y \neq 0 \right\} = \left\{ \frac{(V_m^* A V_m y, y)}{(V_m^* V_m y, y)} \mid y \neq 0 \right\} = \\ &= \left\{ \frac{(H_m y, y)}{(y, y)} \mid y \neq 0 \right\} = \text{Rayleigh quot. of } H_m \supset \text{eigenvalues of } H_m \end{aligned}$$

Answer: Yes

**Question 3 (30 points)** Write down the implicit trapezoidal rule for the initial value problem  $w'(t) = -Aw(t) + g(t)$ ,  $w(0) = w^0$ . After that rewrite the scheme as a linear system where the unknown vector is the solution  $w^{k+1}$  at the next time level, i.e.,  $w^{k+1} \approx w(\tau(k+1))$ , with  $\tau > 0$  being the time step size and  $k$  the time step index.

$$\text{ITR: } \frac{w^{k+1} - w^k}{\tau} = -\frac{1}{2} A w^k - \frac{1}{2} A w^{k+1} + \frac{1}{2} (g^k + g^{k+1})$$

$$w^{k+1} - w^k = -\frac{\tau}{2} A w^k - \frac{\tau}{2} A w^{k+1} + \frac{\tau}{2} (g^k + g^{k+1})$$

$$\underbrace{\left( I + \frac{\tau}{2} A \right)}_{\hat{A}} w^{k+1} = \underbrace{\left( I - \frac{\tau}{2} A \right) w^k + \frac{\tau}{2} (g^k + g^{k+1})}_{\hat{b}}$$

linear system for unknown  $w^{k+1}$