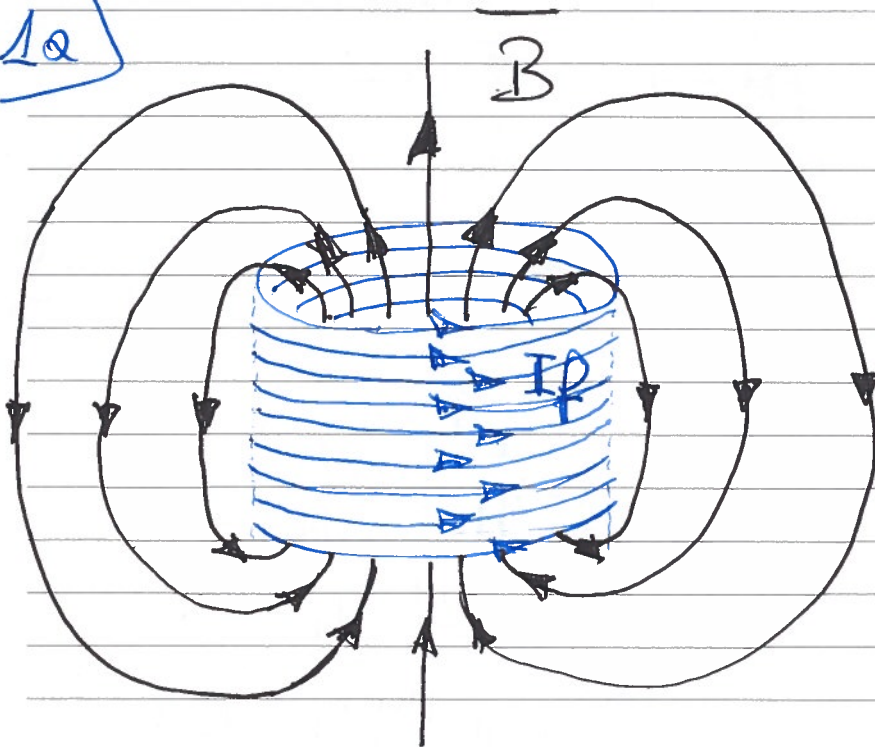


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1a)



⊗ $\vec{B}$ -lines close

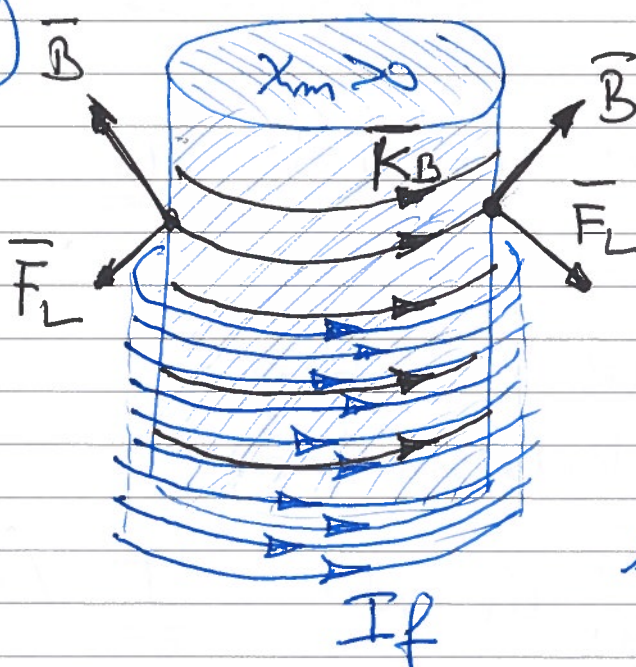
⊗ Direction
(inside +, outside -)
+ R.H.R.

⊗ Not crossing

⊗ Symmetry

⊗ density inside
 $\sim$ uniform.

1b)



⊗ Position & direction
 $\vec{F}_L$

$$\rightarrow \vec{M} = \chi_m \vec{H} = \chi_m H \hat{z}$$

$$\rightarrow \vec{K}_B = \vec{M} \times \hat{n} = \chi_m H (\hat{z} \times \hat{s})$$

$$= \chi_m H \hat{\phi}$$

1c) $\vec{F}_L = \vec{K}_B \times \vec{B}$

points outwards & down

$\rightarrow$ pulled in

2a) NT, they attract each other
(2x right-hand rule)

2b) NT, $\nabla \times \vec{B} = \mu_0 \vec{J}$

"Static" means no time-evolution

$$\rightarrow \nabla \cdot \vec{J} = -\frac{\partial \rho}{\partial t} = 0, \text{ but}$$

this does not imply $\vec{J} = 0$

2c) NT, they bend away from the normal

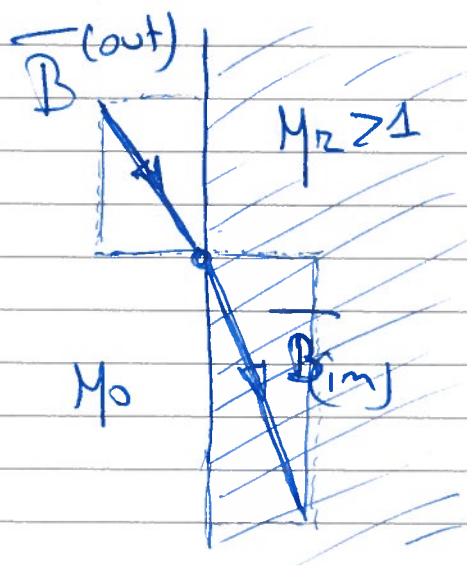
$$B_{\perp}^{(out)} = B_{\perp}^{(in)}$$

$$\text{and } H_{||}^{(out)} - H_{||}^{(in)} = K_f = 0$$

$$\rightarrow H_{||}^{(out)} = H_{||}^{(in)}$$

$$\text{But } B_{||}^{(out)} = \mu_p H_{||}^{(out)}$$

$$< B_{||}^{(in)} = \mu_p \mu_r H_{||}^{(in)}$$

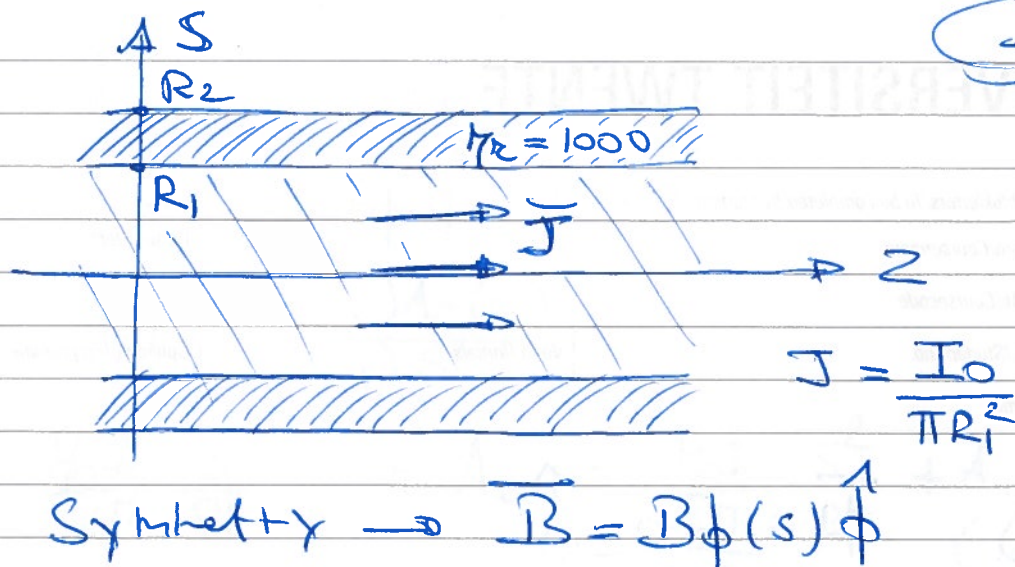


2d) NT, L is the ratio between the magnetic self-flux and the current ($\phi_n = LI$) and only depends on geometry and material properties.

$$2e) \underline{T}, U_n = \iiint \frac{B^2 dz}{2\mu_0} = \iiint \frac{\mu_r^2 \mu_0 H^2 dz}{2}$$

and $H \propto I$ (Ampère)

5a)



Symmetry $\rightarrow \vec{B} = B\phi(s)\hat{\phi}$

$s < R_1$ $\oint \vec{B} \cdot d\vec{e} = \mu_0 I_{enc}$

Ampère-loop circle at $s < R_1$

$$\Rightarrow \begin{cases} \oint \vec{B} \cdot d\vec{e} = 2\pi s B\phi(s) \\ I_{enc} = I_0 \left(\frac{s}{R_1}\right)^2 \end{cases}$$

$$\Rightarrow \boxed{\vec{B} = \frac{\mu_0 I_0}{2\pi} \frac{s}{R_1^2} \hat{\phi}} \quad (s < R_1)$$

$R_1 < s < R_2$ $\oint \vec{H} \cdot d\vec{e} = I_{f, enc} = I_0$

$$\Rightarrow \vec{H} = \frac{I_0}{2\pi s} \hat{\phi}$$

and $\vec{B} = \mu_r \mu_0 \vec{H}$

$$\Rightarrow \boxed{\vec{B} = \mu_r \frac{\mu_0 I_0}{2\pi} \frac{1}{s} \hat{\phi}} \quad (R_1 < s < R_2)$$

$R_2 < s$ Idem for $\vec{H}$, but $\mu_r = 1$

$$\boxed{\vec{B} = \frac{\mu_0 I_0}{2\pi} \frac{1}{s} \hat{\phi}} \quad (R_2 < s)$$

5b) $\vec{A} = A_z(s) \hat{z}$ (current direction)

and $\vec{B} = B_\phi \hat{\phi} = \nabla \times \vec{A}$

$\rightarrow B_\phi = -\frac{\partial A_z(s)}{\partial s}$

① $B_\phi = \frac{\mu_0 I_0}{2\pi} \frac{s}{R_1^2} \rightarrow A_z = -\frac{\mu_0 I_0}{2\pi} \frac{s^2}{2R_1^2} + A_1$
($s < R_1$)

② $B_\phi = \mu_r \frac{\mu_0 I}{2\pi} \frac{1}{s} \rightarrow A_z = -\mu_r \frac{\mu_0 I}{2\pi} \ln(s) + A_2$
($R_1 < s < R_2$)

③ $B_\phi = \frac{\mu_0 I}{2\pi} \frac{1}{s} \rightarrow A_z = -\frac{\mu_0 I}{2\pi} \ln(s) + A_3$
($R_2 < s$)

* Choose e.g. $A=0$ at $s=0 \rightarrow A_1=0$

* Continuity of $\vec{A}$ at $s=R_1 \rightarrow$

$$-\frac{\mu_0 I_0}{2\pi} \frac{1}{2} = -\mu_r \frac{\mu_0 I}{2\pi} \ln R_1 + A_2$$

$$\rightarrow A_2 = \frac{\mu_0 I}{2\pi} \left(\mu_r \ln R_1 - \frac{1}{2} \right)$$

* Continuity of $\vec{A}$ at $s=R_2 \rightarrow$

$$\frac{\mu_0 I_0}{2\pi} \left[\mu_r \ln \left(\frac{R_1}{R_2} \right) - \frac{1}{2} \right] = -\frac{\mu_0 I_0}{2\pi} \ln R_2 + A_3$$

$$\rightarrow A_3 = \frac{\mu_0 I_0}{2\pi} \left[\mu_r \ln \left(\frac{R_1}{R_2} \right) + \ln R_2 - \frac{1}{2} \right]$$

$$\Rightarrow \boxed{\begin{aligned} \vec{A}_1 &= -\frac{\mu_0 I_0}{2\pi} \frac{s^2}{2R_1^2} \hat{z} \\ \vec{A}_2 &= \frac{\mu_0 I_0}{2\pi} \left[\mu_r \ln \left(\frac{R_1}{s} \right) - \frac{1}{2} \right] \hat{z} \\ \vec{A}_3 &= \frac{\mu_0 I_0}{2\pi} \left[\mu_r \ln \left(\frac{R_1}{R_2} \right) + \ln \left(\frac{R_2}{s} \right) - \frac{1}{2} \right] \hat{z} \end{aligned}}$$

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5c) $\vec{H} = \frac{I_0}{2\pi s} \hat{\phi}$

$$\vec{M} = (\mu_r - 1) \vec{H} = (\mu_r - 1) \frac{I_0}{2\pi s} \hat{\phi}$$

$$\vec{K}_B = \vec{M} \times \hat{n}$$

2 surfaces ($s=R_1$ & $s=R_2$)

(*) $s=R_1 \rightarrow \hat{n} = -\hat{s}$

$$\vec{K}_B = (\mu_r - 1) \frac{I_0}{2\pi R_1} (\hat{\phi} \times -\hat{s})$$

$$\boxed{\vec{K}_B = (\mu_r - 1) \frac{I_0}{2\pi R_1} \hat{z}}$$

(*) $s=R_2 \rightarrow \hat{n} = +\hat{s}$

$$\boxed{\vec{K}_B = -(\mu_r - 1) \frac{I_0}{2\pi R_2} \hat{z}}$$

$\vec{J}_B = \nabla \times \vec{M}$ with $\vec{M} = M_\phi(s) \hat{\phi}$

$$\rightarrow \vec{J}_B = \frac{1}{s} \frac{\partial}{\partial s} [s M_\phi(s)] \hat{z} = \frac{1}{s} \frac{\partial}{\partial s} \left[\frac{(\mu_r - 1) I_0}{2\pi} \right]$$

$$\rightarrow \boxed{\vec{J}_B = 0}$$