

## Test T1 Differential Equations & Numerical Methods

Module : AM M6 Dynamical Systems (201500103)  
Date : Tuesday December 3, 2019  
Time : 8:45 - 11:45 uur  
Duration : 180 min (In case of extra time: 225 min)  
: 30 min (In case only Numerical Methods is tested)  
: 150 min (In case only Differential Equations is tested)  
Module-coordinator : B.G. Geurts  
Lecturer DE : H.G.E. Meijer  
  
Test Type : Closed book  
Supplements : None  
Tools allowed : (Graphical) Calculator

### Remarks:

- Motivate your answers.
- This test consists of 3 pages, including this one, and contains 6 exercises.
- For this test you can get 36 points, i.e., the grade =  $1 + \text{points}/4$ . The points for each exercises are mentioned below.
- If you only take Differential Equations, please skip Exc 5 & 6;  
If you only take Numerical Methods, hand in Exc 5 & 6 only. The grading is adjusted accordingly.
- Only use UT exam paper. Write your name and student number on each sheet of paper. Do not hand in your notes on scratch paper.

### Subpoints:

1	4	3a	1	4a	2	5a	1.5
2a	2	3b	2	4b	2	5b	1.5
2b	6	3c	2	4c	3	6a	1.5
2c	1	3d	2	4d	3	6b	1.5

Grade =  $1 + \text{points}/4$

### Exercises Differential Equations

**Exercise 1.** Solve the following initial value problem

$$\frac{dx}{dt} = \sqrt{x-1}, \quad x(0) = 2. \quad (1)$$

Also state the maximal interval of existence.

**Exercise 2.** Consider the matrix and vector

$$A = \begin{pmatrix} 3 & 1 & -4 \\ 1 & -3 & -2 \\ 2 & 1 & -3 \end{pmatrix}, \quad x_0 = \begin{pmatrix} 2 \\ 1 \\ a \end{pmatrix}, \quad a \in \mathbb{R}.$$

- (a) Show using the characteristic polynomial that the eigenvalues of  $A$  are  $\{1, -2, -2\}$ .
- (b) Determine  $e^{At}$ .
- (c) Determine  $a$  such that  $\lim_{t \rightarrow \infty} e^{At} x_0 = 0$ .

**Exercise 3.** Consider the following system

$$\begin{cases} x' = x(2 - x - 2y), \\ y' = y(2 - 2x - y). \end{cases} \quad (2)$$

- (a) Determine the equilibria.
- (b) Determine the type of the equilibria.
- (c) Show that if an orbit starts on the line  $x = y$ , then it stays on that line, i.e., the line is invariant.
- (d) Sketch the complete phase portrait of (2) for  $0 \leq x, y \leq 3$ . Include the nullclines in your sketch.

**Exercise 4.** We consider the following system

$$\begin{cases} \dot{x} = -y + x(2 - x^2 - y^2) + bx^2y, \\ \dot{y} = x + y(2 - x^2 - y^2) - bx^3. \end{cases} \quad (3)$$

- (a) Derive the transformation from Euclidean to polar coordinates in the following way. Start with the relation  $r(t)e^{i\theta(t)} = x(t) + iy(t)$  and differentiate this relation w.r.t. time. Next multiply both sides by  $(x - iy)$  and determine  $\dot{r}$  and  $\dot{\theta}$  from this relation.
- (b) Convert system (3) to polar coordinates.
- (c) Use a theorem to prove that (3) has a periodic orbit if  $b < \frac{1}{2}$ .
- (d) Sketch phase portraits for  $b = 0$  and  $b = 1$  in the  $(x, y)$ -plane.

### T.O.P. for Numerical Methods

### Exercises Numerical Methods

**Exercise 5.** The numerical approximation of the second derivative of a smooth function  $f$  can be expressed using Taylor expansion as

$$D_2(h) = \frac{f(x_0 + h) - 2f(x_0) + f(x_0 - h)}{h^2} = f^{(2)}(x_0) + C h^2 + O(h^4),$$

where  $h > 0$  and  $f^{(2)}(x_0)$  denotes the exact second derivative of  $f$  in  $x_0$ .

- Determine the expression for  $C$ .
- There exists a value  $h_c$  for  $h$  at which the total error is minimal for a given function  $f$ . What is the dominant error contribution in case  $h \ll h_c$ ? And what is it in case  $h \gg h_c$ ?

**Exercise 6.** A numerical approximation of a quantity  $I(h)$  with a small parameter  $h$  yields a sequence of values given in the following table:

$h$	numerical value $I(h)$
1/2	3.26914555200204
1/4	3.26485038742132
1/8	3.26459370399133
1/16	3.26457783407070

- Determine from these data the order of convergence of this process, i.e., determine the value of  $p$  in the relation

$$I(h) = I + a_p h^p + O(h^{p+1}).$$

- Determine the best approximation for  $I$  by extrapolating once. Also specify an estimate for the absolute error.