Test T1 Differential Equations & Numerical Methods

Module

: AM M6 Dynamical Systems (201500103)

Date

: Friday December 20, 2019

Time

: 8:45 - 11:45 uur

Duration

: 180 min (In case of 25% extra time: 225 min)

: 30 min (In case only Numerical Methods is tested)

: 150 min (In case only Differential Equations is tested)

Module-coordinator : B.G. Geurts

Lecturer DE

: H.G.E. Meijer

Test Type

: Closed book

Supplements

: None

Tools allowed

: (Graphical) Calculator

Remarks:

- Motivate your answers.
- This test consists of 3 pages, including this one, and contains 7 exercises.
- For this test you can get 36 points, i.e., the grade = 1+points/4. The points for each exercises
- If you only take Differential Equations, please skip Exc 6 & 7; Grade=1+9*points/30 If you only take Numerical Methods, hand in Exc 6 & 7 only. The grading is adjusted accordingly.
- Only use UT exam paper. Write your name and student number on each sheet of paper. Do not

Subpoints:

1	4	3a	2	4b	2	6a	1.5
2a	5	3b	2	4c	2	1	
2b	2	3c	2	-	3		1.5
2	_	30	3	5	4	7a	1.5
2C	1	4a	2			7b	15

Grade = 1 + points/4

Exercises Differential Equations



Exercise 1. Solve the following initial value problem

$$\frac{dx}{dt} + \cos(t)x(t) = \frac{1}{2}\sin(2t), \qquad x(0) = 1.$$
 (1)

Also state the maximal interval of existence, and plot the solution for $0 \leq t \leq 10$.

Exercise 2. Consider the matrix and vector

$$A = \begin{pmatrix} 4 & 5 \\ 1 & 0 \end{pmatrix}, \quad x_0 = \begin{pmatrix} a \\ 1 \end{pmatrix}.$$

- (a) Determine e^{At} .
- (b) Plot the phase portrait of $x^\prime=Ax$.
- (c) Determine a such that $\lim_{t\to\infty}e^{At}x_0=0.$

Exercise 3. Consider the following system with parameter $b \in \mathbb{R}$

$$\begin{cases} x' = bx + y - 3x(x^2 + y^2) + x(x^2 + y^2)^2, \\ y' = by - x - 3y(x^2 + y^2) + y(x^2 + y^2)^2. \end{cases}$$
 (2)

- (a) Convert system (2) to polar coordinates. If you can't solve this, then proceed with $r'=r(b+r+2r^2)$ and $\theta'=1$.
- (b) Determine the range of \boldsymbol{b} such that (2) has two periodic orbits.
- (c) Sketch the phase portrait of (2) for $b=-1,\,b=1$ and b=3.

Exercise 4. We consider the following system

$$\begin{cases} \dot{x} = y(y-x), \\ \dot{y} = x(x-y) - y^3. \end{cases}$$
 (3)

- (a) Formulate the theorem for Lyapunov stability, including the properties for a Lyapunov function.
- (b) Show that the origin is stable using the function ${\cal V}=x^2+y^2.$
- (c) Prove that the origin is asymptotically stable for (3).

Exercise 5. Prove that the following planar system

$$\begin{cases} \dot{x} = -y(2+xy), \\ \dot{y} = 2x + y - yx^2 - y^3. \end{cases}$$
 (4)

has a periodic orbit.

T.O.P. for Numerical Methods

Exercises Numerical Methods

1. Exercise 6.

(a) What is the expression for the condition number of the problem: 'compute the value of the function f in a point x'? Compute the condition number in case f is given by

$$f(x)=\tanh x=\frac{e^x-e^{-x}}{e^x+e^{-x}}.$$

- (b) Consider x=0.68 with a possible absolute error of 0.01. We wish to compute f(x).
 - (b1) What is the value of the condition number in this case?
 - (b2) Given the condition number from (b1), what can you conclude regarding the relative error with which f(0.68) is computed?
- 2. **Exercise 7.** With the help of a numerical integration process we obtain for a certain integral I the following approximations I(h) as a function of the stepsize h:

	h	I(h)
A	1/2	0.79438324164397
B	1/4	0.85164722970527
C	1/8	0.86270616289176
9	1/16	0.86522491674297
6	1/32	0.86582874610414

- (a) Determine the order p of the numerical integration process based on the data in the table, i.e., determine the value of p from the expression $I(h)=I+c\,h^p+O(h^{p+1})\,,\;p\in\mathbb{N}.$
- (b) Perform one extrapolation to obtain an improved approximation for I. Include an estimate of the absolute error.