Systems Theory (Module 2 — code: 202200238)

Date:

26-01-2024

Time:

13:45–16:45 (till 12:30 for students with special rights)

Place:

Course coordinator:

Gjerrit Meinsma

Allowed aids during test: None

1. Consider the differential equation

$$y^{(2)}(t) + 2y^{(1)}(t) + 5y(t) = u(t).$$



1 is the differential equation asymptotically stable?

 $\gamma_{b}(b)$ Determine all real homogeneous solutions y(t).

(c) Now let u(t) = 10t - 1. Determine all real solutions y(t) of the above DE that satisfy y(0) = 0.



- 2. Suppose a 3rd-order DE has characteristic polynomial $(\lambda + 3)(\lambda^2 + 4\lambda + 5)$. What is its time constant?
- 3. Let $t \in \mathbb{R}$ and

$$A = \begin{bmatrix} 0 & 2 \\ -1 & 3 \end{bmatrix}.$$



- (a) Determine e^{At} .
- (b) Is $\dot{x}(t) = Ax(t)$ asymptotically stable?
- (c) Let $Q = A^{10}$. Determine e^{Qt} .
- 4. Determine a state representation $\dot{x}(t) = Ax(t) + Bu(t)$, y(t) = Cx(t) + Du(t) of the differential equation

$$y^{(2)}(t) - 3y^{(1)}(t) + y(t) = u^{(2)}(t) - 4u^{(1)}(t).$$

5. Let $\beta \in \mathbb{R}$. Consider

$$\begin{split} \dot{x}(t) &= \begin{bmatrix} 0 & 2 \\ -1 & 3 \end{bmatrix} x(t) + \begin{bmatrix} 1 \\ \beta \end{bmatrix} u(t), \\ y(t) &= \begin{bmatrix} 1 & \beta \end{bmatrix} x(t). \end{split}$$

- 2pt
- (a) For which β 's is the system controllable?
- 2p+
- (b) For which β 's is the system observable?
- 2pt
 - (c) For which β 's is the system stabilizable?
- Z ρ^+ (d) Take $\beta = 0$. Determine a stabilizing state feedback u = -Fx.
- $2\rho^{+}$ (e) Take $\beta = 0$. Determine an observer with both observer poles equal to -1.
- (f) Take $\beta = 0$. Is there a static output feedback u = -Hy (with $H \in \mathbb{R}$) that stabilizes the system?

6. Three questions.

2p+ (a) Determine the unobservable subspace of the system

$$\dot{x}(t) = \begin{bmatrix} -2 & 2 \\ -1 & 1 \end{bmatrix} x(t) + \begin{bmatrix} 2 \\ 1 \end{bmatrix} u(t),$$
$$y(t) = \begin{bmatrix} -1 & 1 \end{bmatrix} x(t).$$

 $2\rho^{+}$ (b) Is there an $A \in \mathbb{R}^{2\times 2}$ such that

$$\mathbf{e}^{At} = \begin{bmatrix} \mathbf{e}^{-t} & t \, \mathbf{e}^t \\ \mathbf{0} & \mathbf{e}^t \end{bmatrix} ?$$

2p+— (c) What is the definition of a *detectable* system?

| problem: | 1 | 2 | 3 | 4 | 5 | 6 |
|----------|-------|---|-------|---|-----------|-------|
| points: | 1+2+4 | 2 | 4+1+2 | 2 | 2+2+2+2+2 | 2+2+2 |

Exam grade: 1+9p/36.