

Test exam: Continuous Optimisation 2015

3TU- and LNMB-course, Utrecht.

Monday 4th December 2015

1. Let $f : \mathbb{R}^m \rightarrow \mathbb{R}$ be a convex function $f(y)$ on \mathbb{R}^m and let $A \in \mathbb{R}^{m \times n}$, $b \in \mathbb{R}^m$ be given.

(a) Show that the function $g(x) := f(Ax + b)$ is a convex function of x on \mathbb{R}^n . [3 points]

(b) Suppose that f is strictly convex. Show that then $g(x) := f(Ax + b)$ is strictly convex if and only if A has (full) rank n . [4 points]

Hint: Recall that f is strictly convex if for any $y_1 \neq y_2$, $0 < \lambda < 1$ it holds: $f(\lambda y_1 + (1 - \lambda)y_2) < \lambda f(y_1) + (1 - \lambda)f(y_2)$.

Solution:

(a) For $x_1, x_2 \in \mathbb{R}^n$, $\lambda \in [0, 1]$ we find:

$$\begin{aligned} g(\lambda x_1 + (1 - \lambda)x_2) &= f(A(\lambda x_1 + (1 - \lambda)x_2) + b) \\ &= f(\lambda Ax_1 + (1 - \lambda)Ax_2 + \lambda b + (1 - \lambda)b) \\ &= f(\lambda(Ax_1 + b) + (1 - \lambda)(Ax_2 + b)) \\ f \text{ is convex} &\leq \lambda f(Ax_1 + b) + (1 - \lambda)f(Ax_2 + b) \\ &= \lambda g(x_1) + (1 - \lambda)g(x_2) \end{aligned}$$

(b) “ \Leftarrow ” $\text{rank}(A) = n$ implies: $x_1 \neq x_2 \Rightarrow Ax_1 \neq Ax_2$.

As in (a) for $x_1 \neq x_2$, $\lambda \in (0, 1)$ we obtain:

$$\begin{aligned} g(\lambda x_1 + (1 - \lambda)x_2) &= f(\lambda(Ax_1 + b) + (1 - \lambda)(Ax_2 + b)) \\ &\quad \text{“}f \text{ is strict convex, } Ax_1 + b \neq Ax_2 + b\text{”} \\ &< \lambda f(Ax_1 + b) + (1 - \lambda)f(Ax_2 + b) \\ &= \lambda g(x_1) + (1 - \lambda)g(x_2) \end{aligned}$$

“ \Rightarrow ” Assume $\text{rank}(A) < n$. Then there exist $x_1 \neq x_2$ with $Ax_1 = Ax_2$ and for any $\lambda \in (0, 1)$ we obtain:

$$\begin{aligned} g(\lambda x_1 + (1 - \lambda)x_2) &= f(\lambda(Ax_1 + b) + (1 - \lambda)(Ax_2 + b)) = f(Ax_1 + b) \\ \text{“}g(x_1) = g(x_2)\text{”} &= g(x_1) = \lambda g(x_1) + (1 - \lambda)g(x_2). \end{aligned}$$

So g is not strictly convex.

2. For given $S \subset \mathbb{R}^n$ we define the convex hull $\text{conv}(S)$ by

$$\text{conv}(S) = \left\{ x = \sum_{i=1}^m \lambda_i x_i \mid \sum_{i=1}^m \lambda_i = 1; x_i \in S, \lambda_i \geq 0 \forall i; m \in \mathbb{N} \right\}$$

Show that $\text{conv}(S)$ is the smallest convex set containing S :

- (a) Show that the set $\text{conv}(S)$ is convex with $S \subset \text{conv}(S)$. [3 points]
- (b) Show that for any convex set C containing S we must have $\text{conv}(S) \subset C$. [3 points]
(Hint: You may use without proof any Lemma, Theorem etc. from the course)

Solution:

- (a) Take $x^1, x^2 \in \text{conv}(S)$, $\lambda \in [0, 1]$ (with $x^j = \sum_{i=1}^{m_j} \lambda_i^j x_i^j$, $x_i^j \in S$, $\sum_{i=1}^{m_j} \lambda_i^j = 1$, $\lambda_i^j \geq 0$ for $j = 1, 2$). Then we find:

$$\lambda x^1 + (1 - \lambda)x^2 = \sum_{i=1}^{m_1} \lambda \lambda_i^1 x_i^1 + \sum_{i=1}^{m_2} (1 - \lambda) \lambda_i^2 x_i^2 \in \text{conv}(S)$$

since $\sum_{i=1}^{m_1} \lambda \lambda_i^1 + \sum_{i=1}^{m_2} (1 - \lambda) \lambda_i^2 = 1$ and “coefficients are ≥ 0 ”. Note that (trivially) $S \subset \text{conv}(S)$ holds.

- (b) Let $S \subset C$ with convex C : Take any $x \in \text{conv}(S)$, i.e., $x = \sum_{i=1}^m \lambda_i x_i$ with $\lambda_i \geq 0$, $\sum_{i=1}^m \lambda_i = 1$ and $x_i \in S$ and thus $x_i \in C$. Since C is convex by Lem.2.5 (Jensen inequality) the convex combination x of points $x_i \in C$ is in C . So $\text{conv}(S) \subset C$.

3. Consider with $0 \neq c \in \mathbb{R}^n$ the program:

$$(P) \quad \min_{x \in \mathbb{R}^n} c^T x \quad \text{s.t.} \quad x^T x \leq 1.$$

- (a) Show that $\bar{x} = -\frac{c}{\|c\|}$ is the minimizer of (P) with minimum value $v(P) = -\|c\|$. [2 points]
 ($\|x\|$ means here the Euclidian norm.)
- (b) Compute the solution \bar{y} of the Lagrangean dual (D) of (P). Show in this way [4 points]
 that for the optimal values strong duality holds, i.e., $v(D) = v(P)$.

Solution:

- (a) Either show this “by a sketch”. Or as follows (using Schwarz inequality):

$$\|x\| \leq 1 \text{ implies: } c^T x \geq -\|c\| \|x\| \geq -\|c\|, \text{ and “ } c^T x = -\|c\| \text{” holds iff } x = -\frac{c}{\|c\|}$$

So $\bar{x} = -\frac{c}{\|c\|}$ is the minimizer with $v(P) = c^T(-\frac{c}{\|c\|}) = -\|c\|$.
 (Alternatively find \bar{x} by solving the KKT-conditions.)

(b) The dual (D) is given by

$$(D) \quad \max_{y \geq 0} \psi(y) \quad \text{where } \psi(y) := \min_{x \in \mathbb{R}^n} L(x, y)$$

with Lagrangean function $L(x, y) = c^T x + y(x^T x - 1)$.

We find for $y = 0$: $\psi(0) = -\infty$.

for $y > 0$: The minimizer x of $\psi(y)$ satisfies $\nabla_x L(x, y) = c + 2yx = 0$ or $x = -\frac{1}{2y}c$. So (fill in)

$$\psi(y) = -\frac{1}{2y}c^T c + \frac{1}{4y}c^T c - y = -\frac{1}{4y}c^T c - y.$$

To find an (unconstrained) maximizer of $\psi(y)$ for $y > 0$ we solve

$$\psi'(y) = \frac{1}{4y^2}c^T c - 1 = 0 \quad \text{with solution} \quad \bar{y} = \frac{1}{2}\|c\|.$$

So $v(D) = \psi(\bar{y}) = -\|c\| = v(P)$.

4. Consider the problem (in connection with the design of a cylindrical can with height h , radius r and volume at least 2π such that the total surface area is minimal):

$$(P) : \quad \min f(h, r) := 2\pi(r^2 + rh) \quad \text{s.t.} \quad -\pi r^2 h \leq -2\pi, \quad (\text{and } h > 0, r > 0)$$

- (a) Compute a (the) solution (\bar{h}, \bar{r}) of the KKT conditions of (P). Show that (P) is not a convex optimization problem. [4 points]
- (b) Show that the solution (\bar{h}, \bar{r}) in (a) is a local minimizer. Why is it the unique global solution? [3 points]

Hint: Use the sufficient optimality conditions

Solution:

- (a) We first note that the functions $f(h, r) = 2\pi(r^2 + rh)$ and $g(h, r) := -\pi r^2 h + 2\pi$ are not convex (for $h > 0$). For the objective function f , e.g., this follows by:

$$\nabla f = 2\pi \begin{pmatrix} r \\ 2r + h \end{pmatrix}, \quad \nabla^2 f = 2\pi \begin{pmatrix} 0 & 1 \\ 1 & 2 \end{pmatrix} \quad \text{and thus:} \quad \det \nabla^2 f < 0$$

We now consider the KKT condition: $(\nabla f = -\mu \nabla g, g \leq 0, \mu \cdot g = 0)$

So consider: $2\pi \begin{pmatrix} r \\ 2r + h \end{pmatrix} = \mu \pi \begin{pmatrix} r^2 \\ 2rh \end{pmatrix} \quad (\star)$:

Case $\mu = 0$: leads to $2\pi \begin{pmatrix} r \\ 2r + h \end{pmatrix} = 0$ with solution $(h, r) = (0, 0)$ which is not feasible.

Case $\mu > 0$ and thus $\pi r^2 h = 2\pi$:

The 2 equations in (\star) lead to $\mu = 2/r$ and then $2(2r+h) = \frac{2}{r}2rh$ or $h = 2r$.

By using the (active) constraint we find $\pi r^2 h = 2\pi r^3 = 2\pi$ with solution $r = 1$. So the unique KKT solution is given by $(\bar{h}, \bar{r}) = (2, 1), \bar{\mu} = 2$.

- (b) (We apply the second order sufficient conditions of Th. 5.9 to the nonconvex program (P)). So we will show (for the cone of critical directions $C(\bar{h}, \bar{r})$):

$$d^T \nabla_{h,r}^2 L(\bar{h}, \bar{r}, \bar{\mu}) d > 0 \quad \forall d \in C(\bar{h}, \bar{r}) \setminus \{0\} \quad (\star\star)$$

We compute

$$\begin{aligned} \nabla f(\bar{h}, \bar{r}) &= 2\pi \begin{pmatrix} 1 \\ 4 \end{pmatrix}, & \nabla g(\bar{h}, \bar{r}) &= -\pi \begin{pmatrix} 1 \\ 4 \end{pmatrix}, \\ \nabla^2 L(\bar{h}, \bar{r}, \bar{\mu}) &= 2\pi \begin{pmatrix} 0 & 1 \\ 1 & 2 \end{pmatrix} + 2(-\pi) \begin{pmatrix} 0 & 2 \\ 2 & 4 \end{pmatrix} = -2\pi \begin{pmatrix} 0 & 1 \\ 1 & 2 \end{pmatrix} \end{aligned}$$

and

$$\begin{aligned} C(\bar{h}, \bar{r}) &= \{d \in \mathbb{R}^2 \mid \nabla f(\bar{h}, \bar{r})^T d \leq 0, \nabla g(\bar{h}, \bar{r})^T d \leq 0\} \\ &= \{d \in \mathbb{R}^2 \mid \begin{pmatrix} 1 \\ 4 \end{pmatrix}^T d \leq 0, -\begin{pmatrix} 1 \\ 4 \end{pmatrix}^T d \leq 0\} \\ &= \{\lambda \begin{pmatrix} -4 \\ 1 \end{pmatrix} \mid \lambda \in \mathbb{R}\} \end{aligned}$$

For $d = \lambda(-4, 1)^T \neq 0$, (i.e., $\lambda \neq 0$) we obtain (see $(\star\star)$):

$$\lambda(-4, 1)(-2\pi) \begin{pmatrix} 0 & 1 \\ 1 & 2 \end{pmatrix} \lambda \begin{pmatrix} -4 \\ 1 \end{pmatrix} = \dots = 2\lambda^2\pi 6 > 0 \quad \forall \lambda \neq 0.$$

So $(\bar{h}, \bar{r}) = (2, 1)$ is a local minimizer.

It is the unique (global) minimizer since the point is the only KKT point.

Note that since the linear independency constraint qualification holds ($\nabla g = -\pi \begin{pmatrix} r^2 \\ 2rh \end{pmatrix} \neq 0$, for $r, h > 0$) any local minimizer must be a KKT point. Also note that for feasible $\|(h, r)\| \rightarrow \infty$ also $f \rightarrow \infty$ holds. (To show the latter fact is technically “involved” and was not expected to be done.)

5. Consider the closed set

$$\mathcal{K} = \{\mathbf{x} \in \mathbb{R}^2 \mid x_1 + 2x_2 \geq 0 \text{ and } 3x_1 + x_2 \geq 0\}$$

(a) Prove that \mathcal{K} is a proper cone. [You may assume closure.]

[5 points]

(b) Find the dual cone to \mathcal{K} .

[1 point]

Solution:

(a) In order for a set to be a proper cone it must be a closed, convex, pointed full-dimensional cone. We will assume closure and prove the rest:

- Convex cone: Consider an arbitrary $\mathbf{x}, \mathbf{y} \in \mathcal{K}$ and $\lambda_1, \lambda_2 > 0$. From Theorem 1.3 of the conic optimisation part of the course, if we can show that $\lambda_1\mathbf{x} + \lambda_2\mathbf{y} \in \mathcal{K}$ then we are done.

We have

$$\begin{array}{lll} x_1 + 2x_2 \geq 0, & 3x_1 + x_2 \geq 0, & \lambda_1 > 0, \\ y_1 + 2y_2 \geq 0, & 3y_1 + y_2 \geq 0, & \lambda_2 > 0. \end{array}$$

This implies that

$$\begin{aligned} (\lambda_1\mathbf{x} + \lambda_2\mathbf{y})_1 + 2(\lambda_1\mathbf{x} + \lambda_2\mathbf{y})_2 &= \lambda_1(x_1 + 2x_2) + \lambda_2(y_1 + 2y_2) \geq 0, \\ 3(\lambda_1\mathbf{x} + \lambda_2\mathbf{y})_1 + (\lambda_1\mathbf{x} + \lambda_2\mathbf{y})_2 &= \lambda_1(3x_1 + x_2) + \lambda_2(3y_1 + y_2) \geq 0. \end{aligned}$$

Therefore $\lambda_1\mathbf{x} + \lambda_2\mathbf{y} \in \mathcal{K}$.

- Full-dimensional: Using Definition 1.8, part 2 of the conic optimisation part of the course, this follows from the space being two dimensional and having two linearly independent vectors $\begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix} \in \mathcal{K}$.
- Pointed: We will consider an arbitrary $\mathbf{x} \in \mathbb{R}^2$ such that $\pm\mathbf{x} \in \mathcal{K}$. Using Definition 1.7 of the conic optimisation part of the course, if we can then show that $\mathbf{x} = \mathbf{0}$ then we are done. We have

$$\left. \begin{array}{l} (\mathbf{x})_1 + 2(\mathbf{x})_2 \geq 0 \\ (-\mathbf{x})_1 + 2(-\mathbf{x})_2 \geq 0 \end{array} \right\} \Rightarrow x_1 + 2x_2 = 0,$$

$$\left. \begin{array}{l} 3(\mathbf{x})_1 + (\mathbf{x})_2 \geq 0 \\ 3(-\mathbf{x})_1 + (-\mathbf{x})_2 \geq 0 \end{array} \right\} \Rightarrow 3x_1 + x_2 = 0.$$

Therefore

$$x_1 = \frac{2}{5} \underbrace{(3x_1 + x_2)}_{=0} - \frac{1}{5} \underbrace{(x_1 + 2x_2)}_{=0} = 0, \quad x_2 = \underbrace{(3x_1 + x_2)}_{=0} - 3 \underbrace{x_1}_{=0} = 0.$$

- (b) From Corollary 2.8 of the conic optimisation part of the course and the note on slide 10/31 of the first lecture in the conic optimisation part of the course we have that

$$\mathcal{K}^* = \text{cl conic} \left\{ \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \begin{pmatrix} 3 \\ 1 \end{pmatrix} \right\} = \text{conic} \left\{ \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \begin{pmatrix} 3 \\ 1 \end{pmatrix} \right\}.$$

6. We will consider bounds to the optimal value of the following problem:

$$\begin{aligned} \min_{\mathbf{x}} \quad & 5x_1^2 - 4x_1x_2 - 2x_1 + x_2^2 + 2 \\ \text{s.t.} \quad & x_1^2 + 5x_2^2 - 4x_1x_2 - 8x_2 = 4 \\ & \mathbf{x} \in \mathbb{R}^2. \end{aligned} \tag{A}$$

- (a) Give a finite upper bound on the optimal value of problem (A). [1 point]
- (b) Formulate a positive semidefinite optimisation problem to give a lower bound on the optimal value of problem (A). [2 points]
- (c) Give the dual problem to the positive semidefinite optimisation problem you formulated in part (b) of this question. [1 point]

Solution:

- (a) To find an upper bound we can use any feasible point, $\hat{\mathbf{x}}$. If we limit our search for a feasible point such that $\hat{x}_2 = 0$ then we would have a feasible point if and only if $4 = \hat{x}_1^2 + 5 \cdot 0^2 - 4\hat{x}_1 \cdot 0 - 8 \cdot 0 = \hat{x}_1^2$. Therefore both $\hat{\mathbf{x}} = (2, 0)$ and $\hat{\mathbf{x}} = (-2, 0)$ are feasible points. We only need one point to give us an upper bound, and if we consider the feasible point $\hat{\mathbf{x}} = (2, 0)$ then this gives us the upper bound of

$$\begin{aligned} 5\hat{x}_1^2 - 4\hat{x}_1\hat{x}_2 - 2\hat{x}_1 + \hat{x}_2^2 + 2 &= 5 \cdot 2^2 - 4 \cdot 2 \cdot 0 - 2 \cdot 2 + 0^2 + 2 \\ &= 20 - 0 - 4 + 0 + 2 \\ &= 18 \end{aligned}$$

- (b) Problem (A) is equivalent to

$$\begin{aligned} \min_{\mathbf{x}} \quad & 5x_1^2 - 4x_1x_2 - 2x_1x_3 + x_2^2 + 2x_3^2 \\ \text{s.t.} \quad & x_1^2 + 5x_2^2 - 4x_1x_2 - 8x_2x_3 = 4 \\ & x_3^2 = 1, \quad \mathbf{x} \in \mathbb{R}^3, \end{aligned}$$

which is in turn equivalent to

$$\begin{aligned} \min_{\mathbf{x}, X} \quad & \left\langle \begin{pmatrix} 5 & -2 & -1 \\ -2 & 1 & 0 \\ -1 & 0 & 2 \end{pmatrix}, X \right\rangle \\ \text{s.t.} \quad & \left\langle \begin{pmatrix} 1 & -2 & 0 \\ -2 & 5 & -4 \\ 0 & -4 & 0 \end{pmatrix}, X \right\rangle = 4 \\ & \left\langle \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}, X \right\rangle = 1, \\ & X = \mathbf{x}\mathbf{x}^T, \quad \mathbf{x} \in \mathbb{R}^3, \end{aligned}$$

A lower bound on this is then provided by solving the optimisation problem

$$\begin{aligned} \min_{\mathbf{x}, X} \quad & \left\langle \begin{pmatrix} 5 & -2 & -1 \\ -2 & 1 & 0 \\ -1 & 0 & 2 \end{pmatrix}, X \right\rangle \\ \text{s.t.} \quad & \left\langle \begin{pmatrix} 1 & -2 & 0 \\ -2 & 5 & -4 \\ 0 & -4 & 0 \end{pmatrix}, X \right\rangle = 4 \\ & \left\langle \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}, X \right\rangle = 1, \\ & X \in \mathcal{PSD}^3. \end{aligned}$$

- (c) Considering slide 9/20 of lecture 3 of the conic optimisation part of this course we have that the dual problem is

$$\begin{aligned} \max_{\mathbf{y}} \quad & 4y_1 + y_2 \\ \text{s.t.} \quad & \begin{pmatrix} 5 & -2 & -1 \\ -2 & 1 & 0 \\ -1 & 0 & 2 \end{pmatrix} - y_1 \begin{pmatrix} 1 & -2 & 0 \\ -2 & 5 & -4 \\ 0 & -4 & 0 \end{pmatrix} - y_2 \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} \in \mathcal{PSD}^3. \end{aligned}$$

7. (Automatic additional points)

[4 points]

Question:	1	2	3	4	5	6	7	Total
Points:	7	6	6	7	6	4	4	40

**A copy of the lecture-sheets may be used during the examination.
Good luck!**