

# Re-Exam “Discrete Optimization”

Wednesday, January 18, 2017, 13:00 – 16:00

- Answers have to be in English.
- Use of calculators, mobile phones, and other electronic devices is not allowed.
- The exam consists of six problems. Please start a new page for every problem.
- The total number of points is 50.

## 1. Matroids

Let  $G = (V, E)$  be an undirected, connected graph. Let  $n = |V|$  be the number of vertices of  $G$ . We assume that  $|E| \geq n$ . A 1-tree of  $G$  is a connected spanning subgraph  $L$  that has exactly  $n$  edges. (The name 1-tree comes from the fact that  $L$  consists of a spanning tree plus one additional edge.)

Let  $(E, \mathcal{M})$  be the following independent set system:

- If  $F \subseteq E$  forms a 1-tree, then  $F \in \mathcal{M}$ .
- If  $F' \subseteq F$  and  $F$  is a 1-tree, then  $F' \in \mathcal{M}$ .

(8 points) Prove that  $(E, \mathcal{M})$  is a matroid. To do this, you only have to prove that (M3) holds: If  $A, B \in \mathcal{M}$  and  $|A| < |B|$ , then there exists some edge  $e \in B \setminus A$  with  $A \cup \{e\} \in \mathcal{M}$ .

## 2. NP-Completeness

The hitting set problem **HittingSet** is the following optimization problem:

*Instance:* a finite set  $X$  (called the “universe”); subsets  $S_1, \dots, S_n \subseteq X$ .

*Solution:* a subset  $H \subseteq X$  that satisfies  $H \cap S_i \neq \emptyset$  (this means that  $H$  “hits” all the subsets  $S_1, \dots, S_n$  – hence  $H$  is called a “hitting set”).

*Goal:* minimize  $|H|$ .

The decision version of **HittingSet** is the following problem: Given an instance of **HittingSet** and a number  $k \in \mathbb{N}$ , does there exist a hitting set  $H$  with  $|H| \leq k$ ?

- (a) (7 points) Prove that **HittingSet** is NP-hard. You do not have to prove that the decision version of **HittingSet** is in NP.

*Hint:* **VertexCover** is the following NP-hard problem:

*Instance:* undirected graph  $G = (V, E)$ .

*Solution:*  $U \subseteq V$  such that each edge in  $E$  has at least one endpoint in  $U$ . (Then  $U$  is called a “vertex cover” of  $G$ .)

*Goal:* minimize  $|U|$ .

The decision version of **VertexCover** is the following problem: Given an instance of **VertexCover** and an  $\ell \in \mathbb{N}$ , does there exist a vertex cover  $U$  of  $G$  with  $|U| \leq \ell$ ?

- (b) (7 points) Consider the following algorithm for **HittingSet**, which we call **NAIVE**:

```
1:  $H = \emptyset$ 
2: while there is some  $i$  with  $S_i \cap H = \emptyset$  do
3:    $H = H \cup S_i$ 
4: end while
```

Let  $c_{\max} = \max\{|S_i| \mid 1 \leq i \leq n\}$  be the cardinality of the largest set in the given instance.

Prove that **NAIVE** yields a  $c_{\max}$ -approximation for **HittingSet**. This means that **NAIVE** computes a hitting set  $U$  such  $|U| \leq c_{\max} \cdot |U^*|$ , where  $|U^*|$  is a hitting set of minimum cardinality.

### 3. Pseudo-Polynomial and Approximation Algorithms

Pack is the following optimization problem:

*Instance:* numbers  $a_1, \dots, a_n \in \mathbb{N}$ , a number  $b \in \mathbb{N}$

*Solution:* a subset  $I \subseteq \{1, \dots, n\}$  with  $\sigma(I) = \sum_{i \in I} a_i \leq b$

*Goal:* maximize  $\sigma(I)$ .

- (a) (5 points) Devise an algorithm that solves Pack in time polynomial in  $b$  and  $n$ . It suffices if your algorithm outputs  $\sigma(I^*)$ , where  $I^*$  denotes an optimal solution. Your algorithm does not need to output the set  $I^*$ .

You do not have to prove the correctness of your algorithm.

- (b) (5 points) Devise a polynomial-time algorithm that computes a set  $I$  such that  $\sigma(I) \geq \frac{1}{2} \cdot \sigma(I^*)$ , where  $I^*$  denotes an optimal solution.

This means that your algorithm should be a 2-approximation for Pack.

### 4. Min-Cost Flows

We consider flow networks  $G = (V, E)$  with balances  $b = (b_v)_{v \in V}$  and edge costs  $c = (c_e)_{e \in E}$ , but without edge capacities. This means that  $f$  is a flow if  $f$  assigns a non-negative flow value to each directed edge and satisfies the balance constraints. We assume that there exists a feasible flow  $f$ .

(6 points) Prove that the following two statements are equivalent for all such flow networks:

(I) There exists a minimum-cost flow in  $G$ .

(II) The flow network  $G$  does not contain a directed cycle of negative costs.

## 5. Minimum Spanning Trees

(4 points) Prove the following statement.

For all undirected, connected graphs  $G = (V, E)$  with edge weights  $w$ , the following holds: Let  $t$  be the smallest number such that  $G_t = (V, E_t)$  is connected, where

$$E_t = \{e \in E \mid w_e \leq t\}.$$

Then  $G_t$  contains a minimum spanning tree of  $G$ .

## 6. Miscellaneous Questions

Are the following statements true or false? Justify your answer. This justification can be a short proof, a reference to a theorem of the lecture, a counterexample, ...

- (a) (2 points) For all directed graphs  $G = (V, E)$  with edge lengths  $d$  and  $s, t \in V$ , the following holds:

There exists a shortest  $s$ - $t$  path in  $G$  if and only if

- there exists an  $s$ - $t$  path in  $G$  and
- $G$  does not contain a cycle of negative length.

- (b) (2 points) Let  $\text{PerfectMatch} = \{G \mid G \text{ contains a perfect matching}\}$ . If there is a polynomial-time many-one reduction from 3SAT to  $\text{PerfectMatch}$ , then  $\text{NP} = \text{P}$ .

- (c) (2 points) For all decision problems  $A$  and  $B$  with  $B \subseteq A$ , the following holds: If  $A \in \text{P}$ , then  $B \in \text{P}$ .

(Here,  $B \subseteq A$  means that the set of “yes” instances of  $B$  is a subset of the “yes” instances of  $A$ .)

- (d) (2 points) Let  $G = (V, E)$  be a connected graph consisting of at least three vertices, and let  $T$  be a spanning tree of  $G$ . Then, for all  $X \subseteq V$  with  $\emptyset \neq X \neq V$ , there is exactly one edge in  $T$  crossing the cut  $(X, \overline{X})$ .