

# Exam “Discrete Optimization”

Monday, December 19, 2016, 13:30 – 16:30

- Answers have to be in English.
- Use of calculators, mobile phones, and other electronic devices is not allowed.
- The exam consists of six problems. Please start a new page for every problem.
- The total number of points is 50.

## 1. Traveling Salesman Problem

Our goal is to find an approximation algorithm for **MaxTSP**:

*Instance:* undirected, complete graph  $G = (V, E)$  with edge weights  $w : E \rightarrow \mathbb{R}^+$ .

*Solution:* a Hamiltonian cycle  $H \subseteq E$  of  $G$ .

*Goal:* **maximize**  $w(H) = \sum_{e \in H} w(e)$ .

For an instance  $G = (V, E)$  and  $w$  of MaxTSP, let  $H^*$  be a Hamiltonian cycle of  $G$  of maximum weight.

To approximate MaxTSP, we use the following algorithm:

- 1:  $M = \emptyset$
- 2: **while**  $E \neq \emptyset$  **do**
- 3:     choose the heaviest edge  $e = \{u, v\} \in E$ , breaking ties arbitrarily
- 4:      $M = M \cup \{e\}$
- 5:     remove all edges incident to  $u$  or  $v$  from  $E$  (thus, in particular, we remove  $e$ )
- 6: **end while**
- 7: connect the edges in  $M$  in an arbitrary way to obtain a Hamiltonian cycle  $H$

*In the following, we assume that the number  $n$  of nodes is even.*

- (a) (2 points) Let  $M^*$  be a maximum-weight perfect matching of the graph  $G$  with edge weights  $w$ .

Prove that  $w(M) \geq \frac{1}{2} \cdot w(M^*)$ .

- (b) (2 points) Prove that  $w(M^*) \geq \frac{1}{2} \cdot w(H^*)$ .

- (c) (2 points) Prove that the algorithm given above is a 4-approximation for MaxTSP and has a running-time of  $O(n^2 \log n)$ .

## 2. Shortest Path Trees and Minimum Spanning Trees

(6 points) Let  $G = (V, E)$  be a connected, undirected graph with non-negative edge weights  $w$ . For  $v \in V$ , let  $S_v$  denote a shortest path tree rooted at  $v$ , i.e.,  $S_v$  contains shortest paths from  $v$  to all other nodes in  $G$ . Note that  $S_v$  is not necessarily unique. If  $S_v$  is not unique, you are not allowed to choose which tree you get. This means that the statement in the following must hold for all possible choices of  $S_v$  for  $v \in V$ .

Prove the following statement: There exists a minimum-weight spanning tree  $T$  of  $G$  with

$$T \subseteq \bigcup_{v \in V} S_v.$$

(Here, we consider  $T$  and  $S_v$  for  $v \in V$  as sets of edges.)

## 3. Min-Cost Flows

(10 points) For a flow network  $G = (V, E)$  with edge capacities  $u = (u_e)_{e \in E}$  and balances  $b = (b_v)_{v \in V}$  and a feasible flow  $f$ , let  $H_f = (V, F_f)$  be the following undirected graph:

$$F_f = \{ \{u, v\} \mid \text{both } (u, v) \text{ and } (v, u) \text{ are contained in } G_f \}.$$

Here,  $G_f$  denotes the residual network with flow  $f$ . This means that  $F_f$  contains an undirected edge between nodes  $u$  and  $v$  if and only if both  $(u, v)$  and  $(v, u)$  are present in  $G_f$ .

We call a flow network  $G = (V, E)$  2-cycle-free if there does not nodes  $u, v \in V$  with  $(u, v), (v, u) \in E$ .

Prove that the following two statements are equivalent for all 2-cycle-free flow networks  $G = (V, E)$  with edge capacities  $u = (u_e)_{e \in E}$  and balances  $b = (b_v)_{v \in V}$  and feasible flows  $f$  of this network:

- (I) There exist edge costs  $c : E \rightarrow \mathbb{R}$  such that  $f$  is the *unique* minimum-cost flow with respect to  $c$  in this network.
- (II)  $H_f$  is a forest.

## 4. NP-Completeness

BCSP (short for “bicriteria shortest path”) denotes the following optimization problem:

*Instance:* directed graph  $G = (V, E)$ , nodes  $s, t \in V$ , costs  $c : E \rightarrow \mathbb{N}$ , lengths  $\ell : E \rightarrow \mathbb{N}$ , cost budget  $C \in \mathbb{N}$ .

*Solution:*  $s$ - $t$  path  $Q$  with  $c(Q) = \sum_{e \in Q} c(e) \leq C$ .

*Goal:* minimize length  $\ell(Q) = \sum_{e \in Q} \ell(e)$ .

The decision version of BCSP is the following problem: Given an instance of BCSP and a number  $L \in \mathbb{N}$ , does there exist a solution  $Q$  with  $\ell(Q) \leq L$ ?

- (a) (7 points) Prove that BCSP is NP-hard. You do not have to prove that the decision version of BCSP is in NP.

*Hint:* Knapsack is the following NP-hard problem:

*Instance:* weights  $w_1, \dots, w_n \in \mathbb{N}$ , profits  $p_1, \dots, p_n$ , bound  $W \in \mathbb{N}$ .

*Solution:*  $U \subseteq \{1, \dots, n\}$  with  $w(U) = \sum_{i \in U} w_i \leq W$ .

*Goal:* maximize  $p(U) = \sum_{i \in U} p_i$ .

The decision version of Knapsack is the following problem: Given an instance of knapsack and a  $P \in \mathbb{N}$ , does there exist a feasible solution  $U$  with profit  $p(U) \geq P$ ?

- (b) (7 points) Devise an algorithm that solves BCSP and whose running-time is bounded by a polynomial in  $C$ , the number  $n$  of vertices of  $G$  and the number  $m$  of edges of  $G$ . It suffices if your algorithm outputs the length of a shortest path of costs at most  $C$  – it is not necessary to output the path itself.

You do not have to give a proof of correctness, but you have to explain briefly why your algorithm works and why it has the running-time that you claim.

## 5. 1-Trees

(5 points) Let  $G = (V, E)$  be an undirected graph with non-negative edge weights  $w$ . A 1-tree of  $G$  is a connected subgraph  $L$  that has  $|V| = n$  edges. (The name 1-tree comes from the fact that  $L$  consists of a spanning tree plus one additional edge.)

Consider the following algorithm:

- 1: compute a minimum spanning tree of  $G$  with respect to  $w$
- 2: let  $e$  be an edge of minimum weight among all edges in  $E \setminus T$
- 3:  $L = T \cup \{e\}$

Prove that this algorithm computes a 1-tree of minimum weight.

## 6. Miscellaneous Questions

Are the following statements true or false? Justify your answer. This justification can be a short proof, a reference to a theorem of the lecture, a counterexample, ...

- (a) (2 points) For all directed graphs  $G = (V, E)$  with non-negative edge weights  $w$ , the following holds: If there is a unique edge  $e^* \in E$  of minimum weight, i.e.,  $w_{e^*} = \min\{w_e \mid e \in E\}$ , then for every  $v \in V$ , there exists a shortest path tree rooted at  $v$  that contains  $e^*$ .
- (b) (2 points) If there is a pseudo-polynomial algorithm for TSP, then there is a polynomial-time algorithm for Knapsack.
- (c) (2 points) Let  $(S, \mathcal{I})$  be an independent set system. This means that  $S$  is a finite set and  $\mathcal{I} \subseteq \mathcal{P}(S)$  satisfies (i)  $\emptyset \in \mathcal{I}$  and (ii) for all  $X$  and  $Y$  with  $Y \subseteq X \in \mathcal{I}$ , we have  $Y \in \mathcal{I}$ .

If  $(S, \mathcal{I})$  is not a matroid, then there exist weights for the elements in  $S$  such that the greedy algorithm does not compute an independent set of maximum weight.

- (d) (3 points) For all undirected, complete graphs  $G = (V, E)$  with edge weights  $w$ , the following holds: There exists a number  $t$  such that for all minimum spanning trees  $T$  of  $G$ , we have

$$\max\{w_e \mid e \in T\} = t.$$